

### **General Description**

The MH1683A/MH1683C step-down constant-current high-brightness LED (HB LED) drivers provide a cost-effective design solution for automotive interior/exterior lighting, architectural and ambient lighting, LED bulbs, and other LED illumination applications.

The MH1683A/MH1683C operate from a +6.5V to +65V input voltage range and can provide an output current up to 700mA, if operated up to a temperature of +125°C, or up to a 1A if operated up to a temperature of +105°C. A high-side current-sense resistor adjusts the output current, and a dedicated pulse-width modulation (PWM) input enables pulsed LED dimming over a wide range of brightness levels.

These devices are well suited for applications requiring a wide input voltage range. The high-side current sensing and an integrated current-setting circuitry minimize the number of external components while delivering an average output current with  $\pm 3\%$  accuracy. A hysteretic control method ensures excellent input supply rejection and fast response during load transients and PWM dimming. The MH1683A allows 10% current ripple, and the MH1683C allows 30% current ripple. Both devices operate up to a 2MHz switching frequency, thus allowing the use of small-sized components.

The MH1683A/MH1683C offer an analog dimming feature that reduces the output current by applying an external DC voltage below the internal 2V threshold voltage from TEMP\_I to GND. TEMP\_I also sources 25µA to a negative temperature coefficient (NTC) thermistor connected between TEMP\_I and GND, thus providing an analog thermal-foldback feature that reduces the LED current when the temperature of the LED string exceeds a specified temperature point. Additional features include thermal-shutdown protection.

The MH1683A/MH1683C operate over the -40°C to +125°C automotive temperature range and are available in a thermally enhanced 8-pin SO package.

#### **Applications**

- Architectural, Industrial, and Ambient Lighting
- Automotive RCL, DRL, and Fog Lights
- Heads-Up Displays
- Indicator and Emergency Lighting
- PoE Powered Lighting

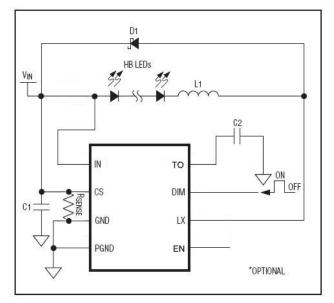
# 2MHz, High-Brightness LED Drivers with Integrated MOSFET and High-Side Current Sense

#### **Benefits and Features**

- Cost-Effective Solution for a Wide Range of LED Lighting Applications
  - 6.5V to 65V Input Voltage Range
  - Output Current Up to 1A
  - ±3% LED Current Accuracy
  - Selectable Dimming Options: Linear or PWM
- Minimal Component Count Saves Cost and Space
  - On-Board 65V, 0.45Ω Power MOSFET
  - Resistor-Programmable Constant LED Current
  - Integrated High-Side Current Sense with 200mV Current-Sense Reference
  - Hysteretic Control: Up to 2MHz Switching
    Frequency
- Protection Features and Wide Operating Temperature Range Improves Lighting Fixture Reliability
  - Thermal-Foldback Protection Dims LEDs to Minimize Overheating
  - Thermal-Shutdown Protection
  - · Available in a Thermally Enhanced 8-Pin SO Package
  - Operation over -40°C to +125°C Temperature Range

Ordering Information and Pin Configuration appear at end of data sheet.

# **Typical Application Circuit**





### **Absolute Maximum Ratings**

IN, CS, LX, DIM to GND	0.3V to +70V
TEMP_I to GND	0.3V to +6V
PGND to GND	0.3V to +0.3V
CS to IN	0.3V to +0.3V
Maximum Current into Any Pin	
(except IN, LX, and PGND)	20mA
Continuous Power Dissipation ( $T_A = +70$	°C)
8-Pin SO (derate 18.9mW/°C above +	70°C)1509.4mW

Operating Temperature Range	
700mA (max) Output Current	40°C to +125°C
1A (max) Output Current	40°C to +105°C
Junction Temperature	+150°C
Storage Temperature Range	65°C to +150°C
Soldering (reflow)	+260°C
Lead Temperature (soldering, 10s)	
Pin-to-Pin ESD Ratings	

### Package Thermal Characteristics (Note 1)

SO-EP

Junction-to-Ambient Thermal Resistance ( $\theta_{JA}$ ).....+53°C/W Junction-to-Case Thermal Resistance ( $\theta_{JC}$ )....+5°C/W

Note 1: Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to **www.led-ics.com** 

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### **Electrical Characteristics**

 $(V_{IN} = +24V, V_{DIM} = V_{IN}, T_A = T_J = -40^{\circ}C$  to  $+125^{\circ}C$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	MAX	UNITS
Input Voltage Range	VIN		6.5		65	V
Ground Current		No switching		1.5		mA
Supply Current		$V_{DIM} < 0.6V, V_{IN} = 12V$		350		μΑ
UNDERVOLTAGE LOCKOUT (UV	LO)					
Undervoltage Lockout	UVLO	$V_{CS}$ = $V_{IN}$ - 100mV, $V_{IN}$ rising until $V_{LX}$ < 0.5 $V_{IN}$		6.25	6.5	v
		$V_{CS}$ = $V_{IN}$ - 100mV, $V_{IN}$ falling until $V_{LX}$ > 0.5V_{IN}			6.0	
Undervoltage-Lockout Hysteresis				0.5		V
SENSE COMPARATOR						
Sense Voltage Threshold High	Vsnshi	MH1683A, V <sub>IN</sub> - V <sub>CS</sub> rising from 140mV until V <sub>LX</sub> > 0.5V <sub>IN</sub> , V <sub>DIM</sub> = 5V	197	205	213	- mV
		$\label{eq:MH1683C} \begin{array}{l} \mbox{MH1683C}, \mbox{V}_{IN} \mbox{-} \mbox{V}_{CS} \mbox{ rising from 140mV} \\ \mbox{until } \mbox{V}_{LX} \mbox{-} \mbox{0.5V}_{IN}, \mbox{V}_{DIM} \mbox{=} \mbox{5V} \end{array}$	218	230	236	
Sense Voltage Threshold Low	V <sub>SNSLO</sub>	$\label{eq:MH1683A, V_{IN} - V_{CS} falling from 260mV} \\ until V_{LX} < 0.5V_{IN} , V_{DIM} = 5V \\ \end{tabular}$	185	190	198	mV
		MH1683C, $V_{IN}$ - $V_{CS}$ falling from 260mV until $V_{LX} < 0.5V_{IN}$ , $V_{DIM} = 5V$	166	170	180	
Propagation Delay to Output High	t <sub>DPDH</sub>	Falling edge of V <sub>IN</sub> - V <sub>CS</sub> from 140mV to 260mV to V <sub>LX</sub> > 0.5V <sub>IN</sub>		50		ns
Propagation Delay to Output Low	t DPDL	Rising edge of V <sub>CS</sub> - V <sub>IN</sub> from 260mV to 140mV to V <sub>LX</sub> < 0.5V <sub>IN</sub>		50		ns
CS Input Current	ICSIN	$V_{IN} - V_{CS} = 200 \text{mV}, V_{IN} = V_{CS}$			3.5	μA



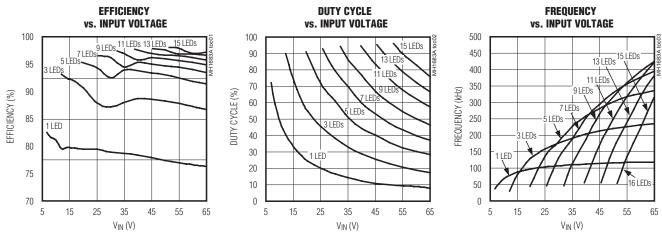
# **Electrical Characteristics (continued)**

 $(V_{IN} = +24V, V_{DIM} = V_{IN}, T_A = T_J = -40^{\circ}C$  to  $+125^{\circ}C$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	MAX	UNITS
INTERNAL MOSFET		·	· ·			·
Durain to Courses Desistences	Deserve	$\label{eq:VIN} \begin{array}{l} V_{IN} = V_{DIM} = 24V, \ V_{CS} = 23.9V, \\ I_{LX} = 700 \text{mA} \end{array}$		0.45	0.9	Ω
Drain-to-Source Resistance	Rdson	$V_{IN} = V_{DIM} = 6.0V, V_{CS} = 5.9V,$ $I_{LX} = 700mA$		1	2	
LX Leakage Current	ILX_LEAK	$V_{\text{DIM}} = 0V, V_{\text{LX}} = 65V$			10	μA
DIM INPUT						
DIM Input-Voltage High	VIH	$V_{IN} - V_{CS} = 100 \text{mV}$	2.8			V
DIM Input-Voltage Low	VIL	$V_{CS} - V_{IN} = 100 \text{mV}$			0.6	V
DIM Turn-On Time	t <sub>DIM_ON</sub>	$V_{DIM}$ rising edge to $V_{LX} < 0.5 V_{IN}$		60		ns
DIM Input Leakage High		$V_{\text{DIM}} = V_{\text{IN}}$		8	15	μA
DIM Input Leakage Low		$V_{\text{DIM}} = 0V$	-3	-1.5	0	μA
THERMAL SHUTDOWN						
Thermal-Shutdown Threshold		Temperature rising		+165		°C
Thermal-Shutdown Threshold Hysteresis				10		°C
THERMAL FOLDBACK	-					
Thermal-Foldback Enable Threshold Voltage	VTFB_ON	V <sub>DIM</sub> = 5V	1.9	2.0	2.12	V
Thermal-Foldback Slope	FBSLOPE	V <sub>DIM</sub> = 5V		0.75		1/V
TEMP_I Output Bias Current	ITEMP_I	$T_A = +25 ^{\circ}C$	25	26.5	28	μA

## **Typical Operating Characteristics**

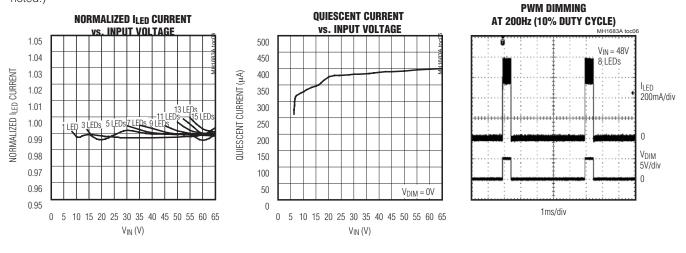
 $(V_{IN} = V_{DIM} = 48V, R_{SENSE} = 0.3\Omega, L = 220\mu H$  (connected between IN and CS). Typical values are at T<sub>A</sub> = +25°C, unless otherwise noted.)





### **Typical Operating Characteristics (continued)**

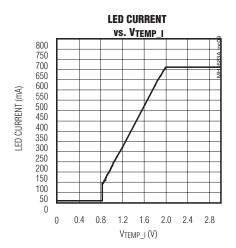
 $(V_{IN} = V_{DIM} = 48V, R_{SENSE} = 0.3\Omega, L = 220\mu H$  (connected between IN and CS). Typical values are at T<sub>A</sub> = +25°C, unless otherwise noted.)

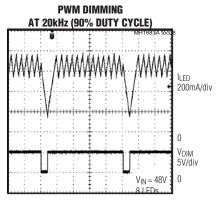


**PWM DIMMING** AT 200Hz (90% DUTY CYCLE ) I<sub>LED</sub> 200mA/div 0 VDIM 5V/div V<sub>IN</sub> = 48V 8 LEDs

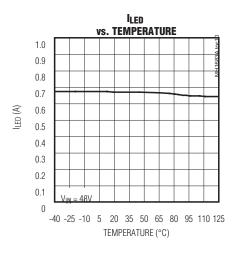
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1ms/div





10µs/div

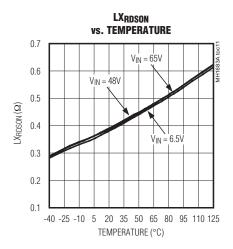


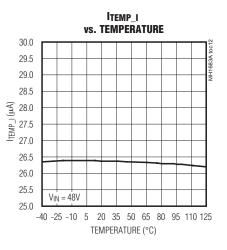
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## **Typical Operating Characteristics (continued)**

 $(V_{IN} = V_{DIM} = 48V, R_{SENSE} = 0.3\Omega, L = 220\mu H$  (connected between IN and CS). Typical values are at T<sub>A</sub> = +25°C, unless otherwise noted.)





#### **Pin Description**

PIN	NAME	FUNCTION	
1	CS	Current-Sense Input. Connect a resistor between IN and CS to program the LED current.	
2	IN	Positive Supply Voltage Input. Bypass with a 1µF or higher value capacitor to GND.	
3	GND	GND Ground	
4	PGND	PGND Power Ground	
5, 6	LX	Switching Node	
7	DIM Logic-Level Dimming Input. Drive DIM low to turn off the current regulator. Drive DIM high to enable the current regulator.		
8	TEMP_I	Thermal Foldback Control and Linear Dimming Input. Bypass with a 0.01µF capacitor to GND if thermal foldback or analog dimming is used. See the <i>Thermal Foldback</i> section.	
_	EP	Exposed Pad. Connect EP to a large-area ground plane for effective power dissipation. Do not use as the IC ground connection.	

## **Detailed Description**

The MH1683A/MH1683C are step-down, constantcurrent, HB LED drivers. These devices operate from a +6.5V to +65V input voltage range. The maximum output is 1A, if the part is used at temperatures up to  $T_A$  = +105°C, or 700mA, if it is used up to  $T_A$  = +125°C. A high-side current-sense resistor sets the output current and a dedicated PWM dimming input enables pulsed LED dimming over a wide range of brightness levels.

A high-side current-sensing scheme and an on-board current-setting circuitry minimize the number of external components while delivering LED current with  $\pm 3\%$  accuracy, using a 1% sense resistor. See Figure 1 for a functional diagram.



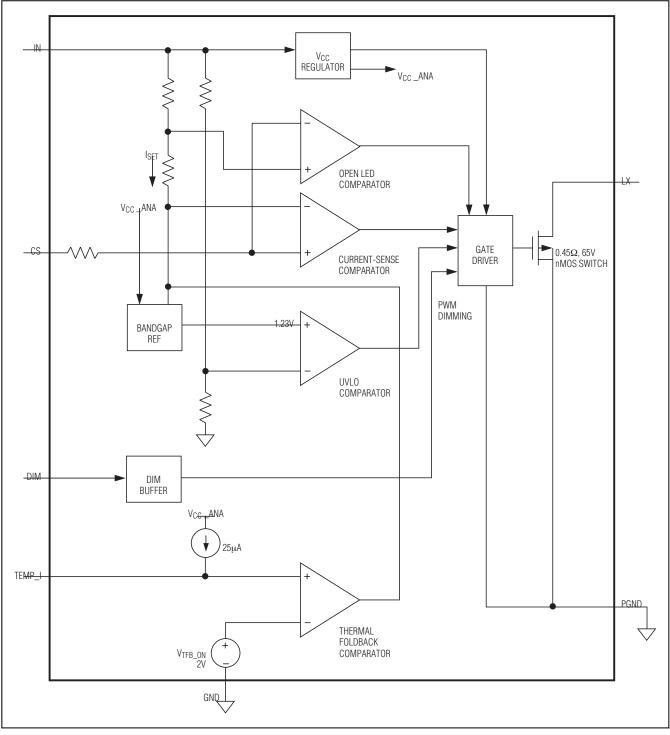


Figure 1. Functional Diagram



#### Undervoltage Lockout (UVLO)

The MH1683A/MH1683C include a UVLO with 500mV hysteresis. The internal MOSFET turns off when V<sub>IN</sub> falls below 5.5V to 6.0V.

#### **DIM Input**

LED dimming is achieved by applying a PWM signal at DIM. A logic level below 0.6V at DIM forces the MH1683A/MH1683Cs' output low, thus turning off the LED current. To turn the LED current on, the logic level at DIM must be greater than 2.8V.

#### **Thermal Shutdown**

The MH1683A/MH1683C thermal-shutdown feature turns off the LX driver when the junction temperature exceeds +165°C. The LX driver turns back on when the junction temperature drops 10°C below the shutdown temperature threshold.

#### **Analog Dimming**

The MH1683A/MH1683C offer an analog-dimming feature that reduces the output current when the voltage at TEMP\_I is below the internal 2V threshold voltage. The MH1683A/MH1683C achieve analog dimming by either an external DC voltage source connected between TEMP\_I and ground or by a voltage on a resistor connected across TEMP\_I and ground induced by an internal current source of 25µA. When the voltage at TEMP\_I is below the internal 2V threshold limit, the MH1683A/MH1683C reduce the LED current. Use the following formula to set the analog dimming current:

$$I_{TF}(A) = I_{LED}(A) \times \left[1 - FB_{SLOPE}\left(\frac{1}{V}\right) \times \left(V_{TFB_{ON}} - V_{AD}\right)(V)\right]$$

where  $V_{TFB_ON} = 2V$  and  $FB_{SLOPE} = 0.75$  are obtained from the *Electrical Characteristics* table and  $V_{AD}$  is the voltage at TEMP\_I.

#### **Thermal Foldback**

The MH1683A/MH1683C include a thermal-fold-

back feature that reduces the output current when the temperature of the LED string exceeds a specified temperature point. These devices enter thermal-foldback mode when the voltage drop on the NTC thermistor, thermally attached to the LEDs and electrically connected between TEMP\_I and ground, drops below the internal 2V threshold limit.

### **Applications Information**

#### Selecting RSENSE to Set LED Current

The LED current is programmed with a current-sense resistor connected between IN and CS. Use the following equation to calculate the value of this resistor:

 $\mathsf{R}_{\text{SENSE}}(\Omega) = \frac{1}{2} \frac{(\mathsf{V}_{\text{SNSHI}} + \mathsf{V}_{\text{SNSLO}})(\mathsf{V})}{\mathsf{I}_{\text{LED}}(\mathsf{A})}$ 

where V<sub>SNSHI</sub> is the sense voltage threshold high and V<sub>SNSLO</sub> is the sense voltage threshold low (see the *Electrical Characteristics* table for values).

#### **Current-Regulator Operation**

The MH1683A/MH1683C regulate the LED current using a comparator with hysteresis (see Figure 2). As the current through the inductor ramps up and the voltage across the sense resistor reaches the upper threshold, the internal MOSFET turns off. The internal MOSFET turns on again when the inductor current ramps down through the freewheeling diode until the voltage across the sense resistor equals the lower threshold. Use the following equation to determine the operating frequency:

$$f_{SW} = \frac{(V_{IN} - nV_{LED}) \times nV_{LED} \times R_{SENSE}}{V_{IN} \times \Delta V \times L}$$

where n is the number of LEDs, V<sub>LED</sub> is the forward voltage drop of 1 LED, and  $\Delta V = (V_{SNSHI} - V_{SNSLO})$ .

#### **Inductor Selection**

The MH1683A/MH1683C operate up to a switching frequency of 2MHz. For space-sensitive applications, the high switching frequency allows the size of the inductor to be reduced. Use the following formula to calculate an approximate inductor value and use the closest standard value:

$$L(approx.) = \frac{(V_{IN} - nV_{LED}) \times nV_{LED} \times R_{SENSE}}{V_{IN} \times \Delta V \times f_{SW}}$$

For component selection, use the MH1683A/C Design Tool available at: www.led-ics.com



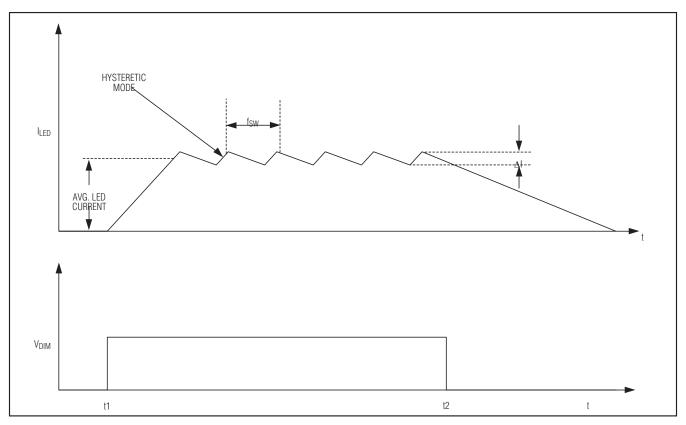


Figure 2. Current-Regulator Operation

#### **Freewheeling-Diode Selection**

For stability and best efficiency, a low forward-voltage drop diode with fast reverse-recovery time and low capacitance is recommended. A Schottky diode is a good choice as long as its breakdown voltage is high enough to withstand the maximum operating voltage.

#### **PCB Layout Guidelines**

Careful PCB layout is critical to achieve low switching losses and stable operation. In normal operation, there are two power loops. One is formed when the internal MOSFET is on and the high current flows from ground through the input cap, RSENSE, the LED load, the inductor, and the internal MOSFET back to ground. The second loop is formed when the internal MOSFET is off and the high current circulates from the input cap positive terminal through RSENSE, the LED load, the inductor, and the freewheeling diode and back to the input cap positive terminal. Note that the current through RSENSE, the LED load, and the inductor is basically DC with some triangular ripple (low noise). The high-noise, large signal, fast transition switching currents only flow through the freewheeling diode to the input cap positive

terminal, or through the MOSFET to ground and then to the input cap positive terminal. Without a proper PCB layout, these square-wave switching currents can create problems in a hysteretic LED driver.

The current control depends solely on the voltage across R<sub>SENSE</sub>. Any noise pickup on this node induces erratic switching of the internal MOSFET (the IC will operate at a much higher frequency). To help prevent this, place RSENSE as close as possible to CS and IN and keep the sense traces short. It is especially important to keep the square-wave switching currents in the freewheeling diode away from RSENSE. To minimize interference, place the freewheeling diode on the opposite side of the IC as RSENSE and position the input capacitor near the diode so it can return the high frequency currents to ground. The layout in Figure 3 should be used as a guideline. The dashed line shows the path of the high frequency components that cause disruption in operation. For a good thermal design, the exposed pad on the IC should solder to a large pad with many vias to the backside ground plane.



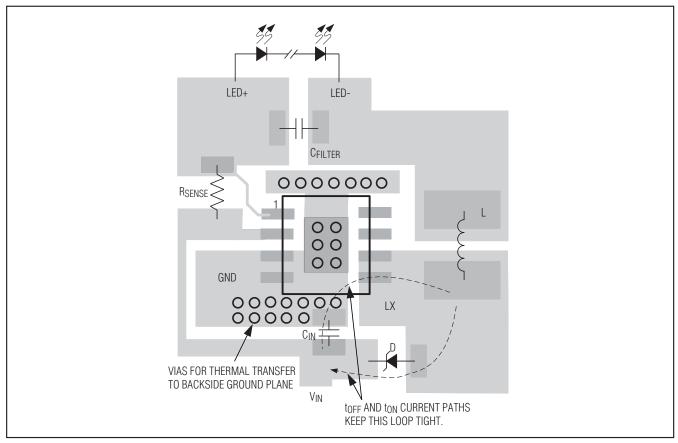
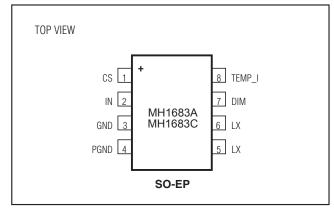


Figure 3. PCB Layout

# **Pin Configuration**



## **Chip Information**

PROCESS: BiCMOS